

Optimal Pricing Strategies for Charging Stations in the Frequency Containment Reserves Market for Vehicle-to-Grid Integration

Guillaume Gasnier, Carlos Canudas-de-Wit

Abstract—Electric vehicles and the electric vehicle charging station infrastructure play crucial roles in sustainable energy systems. We propose an innovative approach that utilizes aggregated electric vehicles for grid-balancing services in the auxiliary market. Our model gives electric vehicle state of charge (SoC) over time and space, considering factors like driver behavior, state of charge levels, and charging/discharging costs. This approach informs decisions about optimal charging times. Charging station operators participate in the frequency containment reserves market in collaboration with aggregators. We introduce an optimization framework which establishes pricing strategies to maximize profits for aggregators and charging station operators while minimizing charging costs for electric vehicle users. Our findings demonstrate the effectiveness of this strategy in realistic simulations, integrating electric vehicle mobility and the electricity frequency containment reserves market.

I. INTRODUCTION

The future of electrification in transportation and use of renewable energy sources are in a transformation phase [1]. The global shift towards renewable energy sources introduces challenges due to their intermittent generation, requiring new energy storage solutions to address supply-demand imbalances [2]. Electrical Vehicles (EVs), with Vehicle-to-Grid (V2G) technology and rapid-response capabilities, can play a pivotal role in grid management [3]. This topic has gained attention recently. In [4], authors suggest that EVs should participate in auxiliary electricity markets. The primary reserve market, also known as "Frequency Containment Reserve" (FCR) stands out as one of the most natural markets for EVs [5], [6]. Numerous studies in the literature have explored this potential. They primarily vary in their approaches to forecasting energy demand at the CSs and in the diverse optimization formulations for their involvement in electricity markets.

For instance, [7] uses aggregated EVs in fast Charging Stations (CSs) led by a Charging Station Operator (CSO) to participate in FCR market. Historical data from the CSs is employed to forecast the vehicles' charging demands. Differences between prediction and real demands are compensated by an additional battery energy storage system located at the CSs. Their goal is to optimize their participation to the electricity market while the prices of EV charging services are kept fixed. Meeting charging demands and bidding requirements are introduced here as a

Guillaume Gasnier, and Carlos Canudas-de-Wit are with Univ. Grenoble Alpes, CNRS, Inria, Grenoble INP, GIPSA-lab, 38000 Grenoble, France (e-mail: {guillaume.gasnier, carlos.canudas-de-wit}@gipsa-lab.fr)

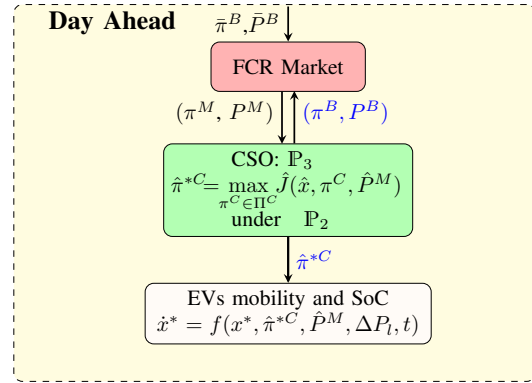


Fig. 1: Day-ahead, CSO declares capacity amount with price. FCR market reports retained capacity and price. CSO decides charging and discharging prices for EVs. Decision variables are in blue.

constraint in the optimization problem. In [8], the authors use statistical data-based models to predict CSs occupancy. The cost function minimize EV battery degradation and maximize the operator earns from their participation to the electricity markets. [9] employs a macroscopic mobility PDE model and EV users behavior to forecast CSs occupancy. Authors compare different CSs pricing strategies to maximize CSs benefits when selling energy to EVs users. Participation in the FCR market is set as a constraint in the optimization formulation, but explicit frequency market models are not include in the study. Vagropoulos and al. [10] use a large EV fleet statistical patterns to design suitable energy demand forecasting at the CSs. With this prediction, the aggregator objective is energy purchased cost minimization (in day-ahead and real-time market) while maximizing the revenue from ancillary market participation. In [11] historical vehicles charging profiles (including public and private CS) are used to forecast energy charging demands. The study addresses the Nordic market, where the EV aggregator bids operate within a framework that separates FCR into two markets for downward and upward regulation. The optimization problem here aims at maximizing the expected profits of EV aggregators on a day-ahead basis.

In this work, we introduce an innovative approach that leverages aggregated electric vehicle charging station to participate in the auxiliary market, enabling grid-balancing services (see Fig.1). A significant contribution of this work, distinct from prior related authors publications [12], [13], and to the other approaches mentioned previously, is the introduction of a new graph model to forecast energy demand at the CSs. The proposed model is derived

under principles of mass conservation and energy balance similar to our previous studies [12], [13], but incorporating fresh elements related to charging stations, including CS occupancy, average state of charge of electric vehicles at CS locations, and power exchange with the grid. This charging station model is seamlessly integrated with an electric vehicle mobility model, which takes into account various allocation ratios based on the average SoC of vehicles near the charging stations and the energy price at the charging station. Moreover, this model is connected with the frequency containment reserves market operation, enabling us to formulate a global optimization problem. Within this framework, we design new pricing strategies with the dual goals of maximizing profits for aggregators and charging station operators, while also minimizing energy charging costs for EV users. Our research findings highlight the effectiveness of this pricing strategy in achieving these objectives, as demonstrated through realistic simulations that encompass EV mobility and the electricity FCR market.

II. AUXILIARY MARKETS

The Frequency Containment Reserve is a vital component of the ancillary service sector. This ancillary service is regulating grid frequency, safeguarding the stability of the power network. Within this domain, there are three distinct components: primary, secondary, and tertiary reserves. FCR is in the primary reserve category, which is characterized by its rapid response capability, acting in less than 15 seconds. Participation in the primary reserve market requires the ability to adjust power consumption, both upward and downward, ensuring a dynamic response to grid frequency fluctuations. The FCR market operates at a European level, featuring varying prices across individual countries, determined by the matching of supply and demand. Market resolution occurs on a day-ahead basis, segmented into six four-hour time blocks.

Throughout the remainder of the paper, we will employ the following upper index:

- M represents market.
- B represents bid.
- C represents CSO.
- D represents demand.
- S represents supply.

Fig. 1 illustrates two key time phases. In the Day ahead phase, market prices for the next day are determined. In this case the CSO is also a charging station. To participate in the FCR market, it must submit available power quantity $P^B \in \mathbb{N}$ in MW and minimum compensation price $\pi^B \in \mathbb{R}$ in €/MW for every time block. Once the FCR market settles, it returns the approved power quantity $P^M \in \mathbb{N}$ in MW and price $\pi^M \in \mathbb{R}$ in €/MW. In the Intraday phase, the CSO sets the charge prices $\pi^C \in \mathbb{R}^+$ in €/kWh. When participating in FCR, the CSO must be capable of both increasing and reducing its charging power. The CSO must also set price π^C in a way that ensures there are always enough vehicles available to meet the grid operator's demands.

A. FCR market settlement process

Settling the FCR market involves solving two Linear Programming (LP) problems. The first LP problem maximizes the amount of power exchanged while ensuring that the highest bid price is lower than the lowest asked price. The second determines the buying/selling price for all participants in the FCR market, ensuring an equitable outcome for all.

Let $P^S \in \mathbb{N}^{n_S}$, and $\pi^S \in \mathbb{R}^{n_S}$ represent vector of proposed supply quantities by the energy suppliers in the FCR market, and their associated prices. Where n_S is the number of supply offers. Without loss of generality, we assume that the CSO makes only one offer and is ordered in the first component of vectors P^S , and π^S i.e.

$$P^S = [P^B, \bar{P}^B]^T \quad (1)$$

$$\pi^S = [\pi^B, \bar{\pi}^B]^T \quad (2)$$

where $\bar{P}^B \in \mathbb{N}^{n_S-1}$, and $\bar{\pi}^B \in \mathbb{R}^{n_S-1}$ represent all other operators offers (see Fig.1). Likewise, $P^D \in \mathbb{N}^{n_D}$ and $\pi^D \in \mathbb{R}^{n_D}$ describe vectors of power demands by the transmission system operators and their respective prices. Here, n_D represents the number of demand offers.

Let $y^S \in \mathbb{N}^{n_S}$ and $y^D \in \mathbb{N}^{n_D}$ represent the vectors representing the energy proportions of each retained offer. Then, the day-ahead market settlement process computes y^S and y^D , by solving the following optimization problem for each of the 4-hours time-sequences:

$$\max_{\{y_i^D\}, \{y_j^S\}} \left\{ \sum_i^{n_S} \pi_i^D y_i^D - \sum_j^{n_D} \pi_j^S y_j^S \right\} \quad (3)$$

under

$$\sum_j^{n_S} y_j^S - \sum_i^{n_D} y_i^D = 0$$

$$0 \leq y_i^D \leq P_i^D, \quad i = 1, \dots, n_D$$

$$0 \leq y_j^S \leq P_j^S, \quad j = 1, \dots, n_S$$

The approved power quantity for the CSO is then,

$$P^M = y_1^S \quad (4)$$

The approved price π^M is obtained by the dual problem. Let $\nu^S \in \mathbb{R}^{n_S}$ and $\nu^D \in \mathbb{R}^{n_D}$ represent Lagrange multipliers for the unitary benefits associated with the various supply and demand offers if the market is cleared at price π^M .

$$\min_{\pi^M, \{\nu_i^D\}, \{\nu_j^S\}} \left\{ \sum_i^{n_D} \nu_i^D P_i^D + \sum_j^{n_S} \nu_j^S P_j^S \right\} \quad (5)$$

under

$$\pi^M - \nu_j^S \leq \pi_j^S, \quad j = 1, \dots, n_S$$

$$-\pi^M - \nu_i^D \leq -\pi_i^D, \quad i = 1, \dots, n_D$$

$$\nu_j^S \geq 0, \quad j = 1, \dots, n_S$$

$$\nu_i^D \geq 0, \quad i = 1, \dots, n_D$$

Table I, illustrates organized offers in the FCR market for a 4-hour time window. The price π^M is determined by the variable in problem (5). Fig. 2 depicts the market resolution

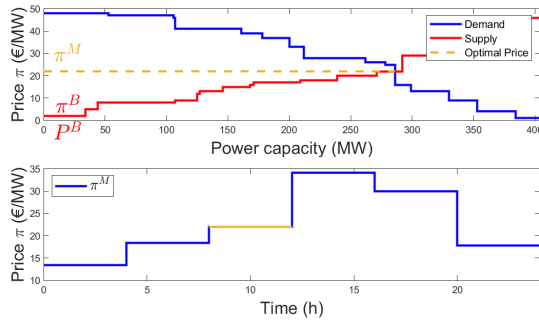


Fig. 2: FCR market price settlement based on Table I and Evolution of FCR prices during a day. In yellow, the price settled on top.

Demand	
π^D (€/MW)	[48,47,47,46,41,41,39,37,33,28,28,26,25,16,13,9,4,4,1,0]
P^D (MW)	[31,22,36,17,1,16,38,17,22,12,22,28,16,8,13,31,23,4,27,34]
Supply	
π^S (€/MW)	[2,5,5,8,8,9,12,13,13,15,16,17,18,20,22,29,32,42,45,46,46]
P^S (MW)	[33,1,10,40,23,18,2,18,1,22,3,38,30,32,21,36,3,16,18,39]

TABLE I: Demand and Supply Data

process. Offers positioned before the intersection point of the demand curve and the supply curve are considered retained offers. The point where these two curves intersect also determines the price per MW. It is important to note that the values provided in this example are fictional, provided for clarity and comprehension of Fig. 2. Fig. 2 also displays the evolution of the settled price in the FCR market for a day across 6 time slots.

III. EVS MOBILITY AND STATE-OF-CHARGE MODELS

Symbol	Description	Domain	Unit
N, N_1, N_2	Number of EVs at the CS, nodes 1 and 2	\mathbb{R}^+	veh
\bar{N}	CS maximum EVs number	\mathbb{R}^+	veh
$\varepsilon, \varepsilon_1, \varepsilon_2$	SoC at the CS, nodes 1 and 2	$[0, 1]$	-
ε_l	SoC EVs start leaving CS	$[0, 1]$	-
β	Split ratio	$[0, 1]$	-
$\sigma, \sigma_1, \sigma_2$	Gating function for CS and nodes 1 and 2	$[0, 1]$	-
$\varphi_{1,2}, \varphi_{2,1}$	Flow from nodes 1 to 2 and form 2 to 1,	\mathbb{R}^+	veh/h
$\varphi_{in}, \varphi_{out}$	Flows entering CS and exiting CS	\mathbb{R}^+	veh/h
$\bar{\varphi}_{CS}, \bar{\varphi}_1, \bar{\varphi}_2$	Flow maximum CS and nodes 1 and 2	\mathbb{R}^+	veh/h
c_i	Constants	\mathbb{R}	-
D	Demand function	\mathbb{R}^+	veh/h
S	Supply function	\mathbb{R}^+	veh/h
Δ_1, Δ_2	Travel energy loss on portion 1 and 2	$[0, 1]$	-
P_{in}, P_{out}	Entering/exiting power	\mathbb{R}^+	kW
P_{CS}	Maximum CS charging power	\mathbb{R}^+	kW
\bar{P}	CS charging power	\mathbb{R}^+	kW
ΔP	Power regulation	\mathbb{R}	kW

TABLE II: Notation summary of the model.

The studied system, illustrated in Fig. 3, consists of a single route connecting two nodes, featuring road links in both directions. A public charging station is positioned along this route. The flow of EVs traveling on this road is divided to access the charging station, based on factors such as the EVs' SoC and the prevailing charging/discharging prices. In the model used, vehicles at the charging station are interconnected. They can both charge and discharge. Once the EVs have completed their charging, the outflow from the charging station returns to the relevant node. Finally, and

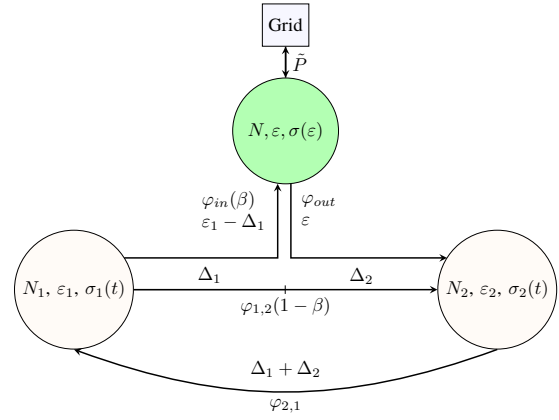


Fig. 3: Studied system mobility and energy visualisation. Yellow circles representing nodes, while green circle symbolizes the dynamics of the charging station.

without loss of generality, EVs return to their origin node to complete the journey.

A. Mobility model

The aggregated mobility model used is based on a set of coupled conservation Ordinary Differential Equations (ODEs) for all time t . It can be easily generalized and validated for a large number of nodes and CSs. Time is implicit in all the following equations of number of vehicles and SoC, $N = N(t)$ and $\varepsilon = \varepsilon(t)$.

The quantity of EVs at the CS, node 1 and node 2 at any given time, denoted as N , N_1 and N_2 , is defined by system Σ_N ,

$$\Sigma_N : \begin{cases} \dot{N} &= \varphi_{in} - \varphi_{out} & (6) \\ \dot{N}_1 &= \varphi_{2,1} - \varphi_{1,2} - \varphi_{in} & (7) \\ \dot{N}_2 &= \varphi_{1,2} + \varphi_{out} - \varphi_{2,1} & (8) \end{cases}$$

Here, $\varphi_{j,i}$ represents the flow of EVs from node j to node i . φ_{in} and φ_{out} are flows entering and exiting the CS. It is important to note that vehicles leaving the CS directly merge with the vehicles at node 2. Entering and exiting CS flows are defined as follows.

$$\varphi_{in} = \min \{ \beta D_1, S \} \quad (9)$$

$$\varphi_{out} = \min \{ D, S_2 \} = D \quad (10)$$

$$\varphi_{1,2} = \min \{ (1 - \beta) D_1, S_2 \} = (1 - \beta) D_1 \quad (11)$$

$$\varphi_{2,1} = \min \{ D_2, S_1 \} = D_2 \quad (12)$$

The demand functions D , D_1 , and D_2 describe the flow of EVs that would like to leave, while the supply functions S , S_1 , and S_2 represent the inflows that can be allowed to enter. The split ratio β represents the proportion of vehicles departing from node 1 and desiring to charge. For the sake of simplicity, and except for the charging station node, we do not consider congestion propagation in the origin/destination nodes. The underlying assumption is that all demand can be fully served in the nodes one and two. As a consequence, at the exception of equation (9), the expression of (10),(11) and (12) simplifies as described above, with:

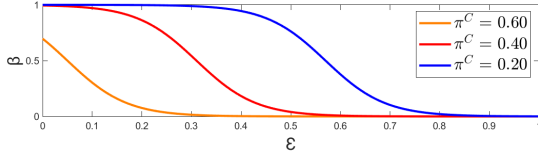


Fig. 4: An example of the splitting ratio function as a function of the state of charge for different charging station prices π^C . $c_1 = 0.83$, $c_2 = 1.3$ and $c_3 = 0.06$.

$$S = \min\{\omega(\bar{N} - N), \bar{\varphi}_{CS}\} \quad (13)$$

$$D = \sigma(\varepsilon) \min\{v_c N, \bar{\varphi}_{CS}\} \quad (14)$$

$$D_1 = \sigma_1(t) \min\{v_1 N_1, \bar{\varphi}_1\} \quad (15)$$

$$D_2 = \sigma_2(t) \min\{v_2 N_2, \bar{\varphi}_2\} \quad (16)$$

where \bar{N} is the maximum CS capacity, $\bar{\varphi}_{CS}$ the maximum inflow/outflow (we assume they are equal) to enter or to leave the CS, and ω the "speed" of filling of the CS. $\sigma(\varepsilon) \in [0, 1]$ is a gating function depending on the average charge level ε of all vehicles parking at the CS. We propose the following function

$$\sigma(\varepsilon) = \begin{cases} 0, & \varepsilon < \varepsilon_l \\ \frac{\varepsilon - \varepsilon_l}{1 - \varepsilon_l}, & \varepsilon \geq \varepsilon_l \end{cases} \quad (17)$$

Our hypothesis allows vehicles to leave (linearly) only after the SoC reaches the average value of $\varepsilon_l < 1$. The constant $v_c > 0$ defines the "charging speed" depending on the average power of the charging stations. For nodes 1 and 2, v_1 and v_2 define the speeds at which vehicles leave their respective nodes, and φ_1 and φ_2 represent the maximum exit flows of nodes 1 and 2, respectively. Finally, $\sigma_1(t) \in [0, 1]$, and $\sigma_2(t) \in [0, 1]$ are the time-depending gating functions as defined in [12]. They provide operational time profiles during the journey for the considered case. The last parameter is the split ratio β that defines the EVs flow proportion that want to charge as defined in [9]. We assume that this utility function will depend on both: the state of charge ε_1 , and the charging station price π^C .

$$\beta(\varepsilon_1, \pi^C) = 1 - \left(1 + e^{-\frac{\varepsilon_1 - c_1 + c_2 \pi^C}{c_3}}\right)^{-1} \quad (18)$$

where c_i are constants. $c_1 > 0$ allows to change the position of the sigmoid's inflection (decaying) point. $c_2 > 0$ weights the influence of the variation in π^C on the inflection point, and $c_3 > 0$ tunes the sigmoid's slope.

B. Energy model

Let E , E_1 and E_2 denote the aggregated energy in the CS and in each node, respectively, then

$$E = c\varepsilon N \quad (19)$$

$$E_1 = c\varepsilon_1 N_1 \quad (20)$$

$$E_2 = c\varepsilon_2 N_2 \quad (21)$$

where $\varepsilon, \varepsilon_1, \varepsilon_2 \in [0, 1]$ describe the state of charge at each node, and c is the average battery capacity of vehicles. Now from energy balance at each node we have:

$$\dot{E} = P_{in} - P_{out} + \tilde{P} \quad (22)$$

$$\dot{E}_1 = P_{in,1} - P_{out,1} \quad (23)$$

$$\dot{E}_2 = P_{in,2} - P_{out,2} \quad (24)$$

The power vehicle flows (with units kW·vehicles) are defined as the product of the vehicle flows [vehicles/hr], the state of charge at the inputs/outputs of each node, and the mean battery capacity [kWh].

$$P_{in} = c\varepsilon_{in}\varphi_{in} = c(\varepsilon_1 - \Delta_1)\varphi_{in} \quad (25)$$

$$P_{out} = c\varepsilon\varphi_{out} \quad (26)$$

$$P_{in,1} = c(\varepsilon_2 - \Delta_1 - \Delta_2)\varphi_{2,1} \quad (27)$$

$$P_{out,1} = c\varepsilon_1\varphi_{1,2} \quad (28)$$

$$P_{in,2} = c((\varepsilon - \Delta_2)\varphi_{out} + \varphi_{1,2}(\varepsilon_1 - \Delta_1 - \Delta_2)) \quad (29)$$

$$P_{out,2} = c\varepsilon_2\varphi_{2,1} \quad (30)$$

where Δ_1 and Δ_2 represent the traveling losses between nodes (see Fig. 3). \tilde{P} is the injected/extracted power Kw from the grid at the CS. It is defined as follows

$$\tilde{P} = \begin{cases} 0, & \varepsilon = 1 \\ P_{CS}N + (\Delta P - P^M) & \varepsilon < 1 \end{cases} \quad (31)$$

The first terms $P_{CS}N$ indicate the "nominal" power injected per charge station point, with P_{CS} being the average power per charging station point. The terms within the parenthesis represent the difference between the approved power P^M as settled in the day-ahead and intraday market, and ΔP , representing the power that the Transmission System Operator (TSO) requests the CSO as a consequence of the mismatch between the power supply and the load demand. By definition, ΔP falls within the range of $[-P^M, P^M]$ and changes every 15 minutes. For the purpose of this study, we assume that ΔP is a random variable with $|\Delta P| \leq P^M$.

Finally, to derive the time variation of the state of charge equations at the CS (a similar procedure can be followed for the other nodes), we first take the time derivatives of E ,

$$\dot{E} = c(\dot{N}\varepsilon + N\dot{\varepsilon}) \quad (32)$$

then, we insert (22), and (6) in the above equation, yielding

$$(\varphi_{in} - \varphi_{out})\varepsilon + \dot{\varepsilon}N = (\varepsilon_1 - \Delta_1)\varphi_{in} - \varepsilon\varphi_{out} + \frac{\tilde{P}}{c} \quad (33)$$

from which we get

$$\dot{\varepsilon} = \frac{1}{N} \left[(-\varepsilon + \varepsilon_1 - \Delta_1)\varphi_{in} + \frac{\tilde{P}}{c} \right] \quad (34)$$

$$\Sigma_{\varepsilon} : \begin{cases} \dot{\varepsilon}_1 = \frac{1}{N_1} [-\varepsilon_1 + \varepsilon_2 - \Delta_1 - \Delta_2]\varphi_{2,1} & (35) \\ \dot{\varepsilon}_2 = \frac{1}{N_2} [(\varepsilon - \varepsilon_2 - \Delta_2)\varphi_{out} + & (36) \\ (\varepsilon_1 - \varepsilon_2 - \Delta_1 - \Delta_2)\varphi_{1,2}] \end{cases}$$

where (35) and (36) are obtained following the same procedure that (34).

IV. MODEL INSTANTATION

In this section, we assemble the full model and provide detailed explanations of how all the components depicted in Fig. 1 are interconnected.

A. mobility and SoC model

We rewrite the mobility and SoC model in a compact form, by defining $x \in \mathbb{R}^6$ as

$$x = [N, N_1, N_2, \varepsilon, \varepsilon_1, \varepsilon_2]^T \quad (37)$$

and

$$\dot{x} = \begin{bmatrix} f_N(x, \pi^C, t) \\ f_{\varepsilon}(x, \pi^C, P^M, \Delta P, t) \end{bmatrix} = f(x, \pi^C, P^M, \Delta P, t) \quad (38)$$

Here, $f_N(x, \pi^C, t)$ and $f_\varepsilon(x, \pi^C, P^M, \Delta P, t)$ represent the right-hand functions of systems Σ_N and Σ_ε , respectively. It is important to note that π^C serves as our control variable to be optimized by the CSO, which will be defined in the following section in connection with the optimization problem. Additionally, π^C is assumed to remain constant for the duration of a day.

B. FCR market model

The CSO proposes a pair of bids (P_k^B, π_k^B) every 4 hours, at time instants $t_k = 4(k-1)$ [hr], where $k \in \mathbb{Z}_k \triangleq 1, 2, \dots, 6$. Subsequently, the FCR market settlement returns the corresponding approved power and prices (P_k^M, π_k^M) .

The CSO's objective is to maximize P_k^B to increase its potential power bid based on the predicted power of the connected EVs to the charging stations: $P_{CS}N(\tau)$, where τ represents the relevant time instance.

$$P_k^B = \Phi(N(\tau)) \triangleq \min_{t_k < \tau < t_{k+1}} \left\{ \frac{P_{CS}N(\tau)}{2} \right\} \quad (39)$$

Here, Φ is a function dependent on N that maximizes the allocated capacity (EVs flexibility) to enter the FCR market. We take half of this capacity to participate in the entire upward/downward regulation mechanism, allowing the CSO to offer $\pm P_k^B$ power regulation.

The bid price π_k^B is generally set through complex economic mechanics beyond the scope of this study. For the purposes of this work, we assume $\pi_k^B = 0$, ensuring that the entirety of the bid offer P_k^B will be retained during the market settlement process. Therefore, we have:

$$P_k^M = P_k^B \quad \forall k \in \mathbb{Z} \quad (40)$$

Finally the returned price from the FCR market is given by:

$$\pi_k^M = \Psi(P_k^B, \pi_k^B) \quad (41)$$

where Ψ represents the map associated to the optimisation problem (3)-(5).

C. TSO power requests

The last component to be defined in the model, which introduces time-dependence in the right-hand side of equation (38), is $\Delta P(t) \in [-P^M, P^M]$. This term describes the real-time power requested by the TSO from the CSO. It is related to the mismatch between power supply and load demand, primarily caused by uncertainty in renewable energy sources (RES) production, among other factors. Here, we model $\Delta P(t)$ as a discrete function with time steps t_l :

$$\Delta P_l \triangleq \text{Rand}_l P_k^M \quad (42)$$

where Rand_l represents a random number uniformly distributed between $[-1, 1]$. Each realization of Rand_l occurs every 15 minutes at time instants $t_l = (l-1)/4$ [hr], where $l \in \mathbb{Z}_l \triangleq 1, 2, \dots, 96$, as mandated by the TSO during real-time operation (see [5]).

D. Integrated model

Integrating the previous components into the general model (38), we have, $\forall \tau \in \mathbb{I}k \triangleq [tk, t_{k+1})$, $\forall k \in \mathbb{Z}_k$ and $l \in \mathbb{Z}_l$.

$$\dot{x}(t) = f(x(t), \pi^C, \Phi(x(\tau)), \Delta P_l, t) \quad (43)$$

where $\Phi(x(\tau)) = \Phi(N(\tau)) = P_k^M$.

Remark 1: Unlike conventional players in the FRC market, who have backup power from generators under their control, the power supply for a CSO depends on the mobility of EVs and their presence at the charging station. Therefore, it is crucial for the CSO to have an electromobility model that can forecast the potential occupancy at the CS. This prediction, in turn, enables the calculation of the variable P^M to participate in the day-ahead market.

Remark 2: It is important to note that solving equation (43) is not a straightforward task, primarily due to non-causal components arising from the computation of P_k^M . Additionally, it contains random elements resulting from ΔP_l . Nevertheless, we can address this challenge by transforming equation (43) into two optimization problems with associated constraints, as demonstrated below.

Problem 1: Solving the differential equation (43) is equivalent to solve the following optimization problem. \mathbb{P}_1 : Given ΔP_l , solve $\forall k \in \mathbb{Z}_k$:

$$P_k^M = \max_{\lambda_k \geq 0} \lambda_k \quad (44)$$

under

$$\dot{x}(t) = f(x(t), \pi^C, \lambda_k, \Delta P_l, t) \quad (45)$$

$$0 \leq \lambda_k \leq \min_{\tau \in \mathbb{I}k} \left\{ \frac{P_{CS}N(\tau)}{2} \right\} \quad (46)$$

E. Numerical model evaluation: study case

For a numerical evaluation of the proposed model, we consider a highly aggregated representation of mobility in a mid-sized city in France, specifically Grenoble. By 2030, it is expected that there will be approximately 30% of EVs, corresponding to a total of $N + N_1 + N_2 = 100,000$ EVs in circulation within the metropolitan area. Let's assume that there is one public charging station for every 10 EVs, resulting in an aggregated CS capacity of $\bar{N} = 10,000$. The nominal charging cost is defined based on current rates as $\pi_n^C = \pi^C = 0.40$ €/kWh. The average battery capacity of the vehicles is $c = 40$ kWh, and the average maximum charging station power for one vehicle is $P_{CS} = 40$ kW. We assume that the average round trip between origins/destinations results in a daily energy loss of 20% of the battery capacity, *i.e.*, $\Delta_1 = \Delta_2 = 0.05$. All parameters for the model are given in Table III. The initial values of the system are $N(0) = 500$, $N_1(0) = 79,500$, $N_2(0) = 20,000$, $\varepsilon(0) = 0.8$, $\varepsilon_1(0) = 0.36$, and $\varepsilon_2(0) = 0.47$.

Symbol	Value	Unit	Symbol	Value	Unit
w	50	km/h	ε_l	0.9	1
vc	50	km/h	P_{CS}	40	kW
v_1	50	km/h	c	40	kWh
v_2	50	km/h	Δ_1	0.05	1
\bar{N}	10000	veh	Δ_2	0.05	1
φ_{CS}	20000	veh/h	c_1	0.83	1
φ_1	20000	veh/h	c_2	1.3	1
φ_2	20000	veh/h	c_3	0.06	1

TABLE III: Simulation parameters and their values.

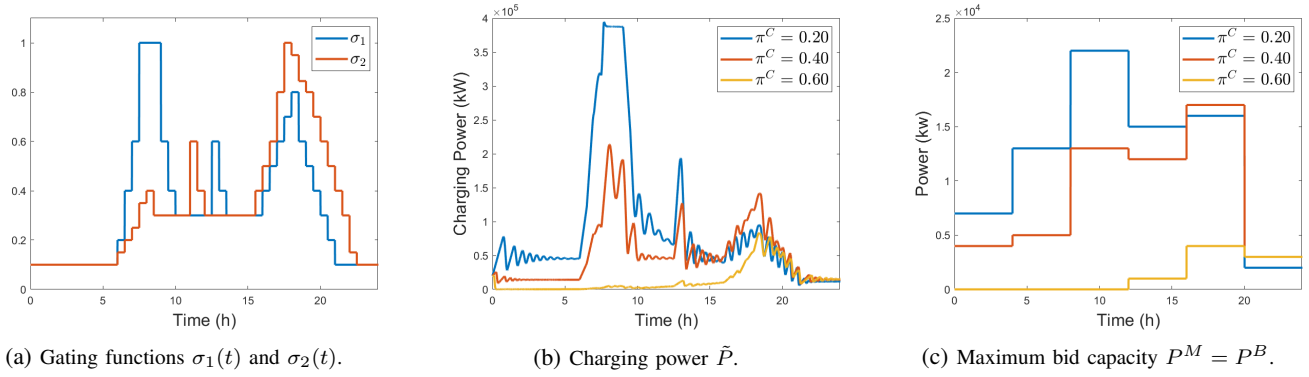


Fig. 5: Numerical results from problem \mathbb{P}_1 . a) Time-profiles of the used mobility gating functions $\sigma_1(t)$ and $\sigma_2(t)$, b) resulting charging power, and c) Maximum bid capacity $P^B = P^M$, as a function of different prices $\pi^C = 0.2, 0.4, 0.6$ €/kWh.

Traffic flow profiles represent typical ring road flows, allowing us to define the gating functions $\sigma_1(t)$ and $\sigma_2(t)$ as shown in Fig. 5a. These time-profiles reflect minimal night traffic, with significant peaks occurring during morning and evening rush hours, as expected, and smaller peaks during the midday break. Fig. 5b illustrates the injected energy at the charging station throughout the day, defined as \tilde{P} . Additionally, Fig. 5b provides information about the number of vehicles at the charging station. The three mobility peaks during the day are reflected in the charging station. The number of vehicles directly affects the capacity that a charging station can offer for sale in the FCR market, as shown in Fig. 5c.

V. OPTIMAL ENERGY-PRICE STRATEGY

In this section, we start by introducing the utility function earmarked for optimization. Next, we present a feasible forecasting model, along with an upper limit on utility to guide the optimization procedure. Finally, we outline and propose a solution for the optimal energy-price optimization problem.

A. Utility function

For each day, the CSO must set π^C while seeking to maximize the gains achieved during the day. The CSO has two different sources of revenue. The first source is the earnings from selling energy to EVs, given by $\int_0^T \pi^C \tilde{P} dt$, while the second source is the earnings from selling capacity in the FCR market, calculated as $\sum_{k=1}^6 \pi_k^M P_k^M$ for each 4-hour block k . Therefore, we have the function J that calculates the total earnings for the full day, *i.e.*, $t \in [0, T]$, with $T = 24$ hrs:

$$J(x, \pi^C, P^M, \pi^M) = \int_0^T \pi^C \tilde{P} dt + \sum_{k=1}^6 \pi_k^M P_k^M \quad (47)$$

The ideal optimization problem aims to find the values of π^C that maximize the earnings given by the function J under the system dynamics (43), or equivalently, under the solution of \mathbb{P}_1 , *i.e.*

$$\begin{aligned} \pi^{*C} &= \max_{\pi^C \in \Pi^C} J(x, \pi^C, P^M, \pi^M) \\ &\text{under } \mathbb{P}_1 \end{aligned} \quad (48)$$

The optimization is mathematically solvable under the condition that we possess the following information: 1) the results of the FCR market settlement, which provide P^M and π^M , and 2) the grid's regulation demands ΔP_l . However 1) and 2) are unknown when we want to solve \mathbb{P}_1 , it is important to note that π^M becomes known only after the market clears and cannot be predicted in advance. Additionally, real-time knowledge is required for ΔP_l . Hence, to make the optimization problem feasible within the constraints of day-ahead market deadlines, we must rewrite the "ideal" optimization problem.

To accomplish this, we initially introduce a modified model that supports forecasting and optimization, where problem \mathbb{P}_1 is modified through the incorporation of bounds on ΔP_l , resulting in additional inequality constraints. Subsequently, we present a quantifiable upper limit on J . This process allows us to form the practical and achievable optimization problem.

B. Model for forecasting and optimization

Given that $\Delta P_l \leq P^M$ is unknown, but upper bounds are known by construction, expressed as $|\Delta P_l| \leq P^M$, Problem \mathbb{P}_1 can then be modified by explicitly incorporating these bounds, resulting in additional inequality constraints.

Problem 2: The only feasible solution, considering both the upper and lower bounds of the random variable ΔP_l , for solving the differential equation (43), is given by the solution of the following optimization problem.

\mathbb{P}_2 : For all $k \in \mathbb{Z}_k$, $l \in \mathbb{Z}_l$ solve:

$$\hat{P}_k^M = \max_{\lambda_k \geq 0} \lambda_k \quad (49)$$

under

$$\dot{\hat{x}}(t) = f(\hat{x}(t), \pi^C, \lambda_k, \Delta \hat{P}_l, t) \quad (50)$$

$$0 \leq \lambda_k \leq \min_{\tau \in \mathbb{I}_k} \left\{ \frac{P_{CS} \hat{N}(\tau)}{2} \right\} \quad (51)$$

$$\Delta \hat{P}_l \leq \lambda_k \quad (52)$$

$$\Delta \hat{P}_l \geq -\lambda_k \quad (53)$$

where $\Delta \hat{P}_l$ acts here as a slack variable. Note that for each run of k , we consider all possible values of ΔP_l in the corresponding time slot \mathbb{I}_k . A solution with reduced complexity could alternatively be found by assuming that ΔP_l is constant in the time interval \mathbb{I}_k , albeit at the cost of some conservatism in the solutions.

C. Computable utility upper bound

From the definition of \tilde{P} , and the fact that $-P^M \leq \Delta P \leq P^M$, we have

$$\tilde{P} = P_{CS}N + (\Delta P - P^M) \leq P_{CS}N \quad (54)$$

Therefore,

$$J = \int_0^T \pi^C \tilde{P} dt + \sum_{k=1}^6 \pi_k^M P_k^M \quad (55)$$

$$\leq \int_0^T \pi^C P_{CS}N dt + \sum_{k=1}^6 \pi_k^M P_k^M \quad (56)$$

$$\leq \int_0^T \pi^C P_{CS}N dt + \pi_{max}^M \sum_{k=1}^6 P_k^M \quad (57)$$

where π_{max}^M is an upper bound on π_k^M . Based on this upper bound, we introduce the utility \hat{J} , which depends only on computable quantities derived from the forecasting model, *i.e.*

$$\hat{J}(\hat{x}, \pi^C, \hat{P}^M) = \int_0^T \pi^C P_{CS} \hat{N} dt + \pi_{max}^M \sum_{k=1}^6 \hat{P}_k^M \quad (58)$$

where \hat{N} , and \hat{P}_k^M are obtained from Problem \mathbb{P}_2 . We are now in position to formulate our final optimal energy-price strategy.

Problem 3: The computable optimal energy-price strategy consist in solving the following optimal problem. \mathbb{P}_3 : For all $k \in \mathbb{Z}_k, l \in \mathbb{Z}_l$ solve:

$$\hat{\pi}^{*C} = \max_{\pi^C \in \Pi^C} \hat{J}(\hat{x}, \pi^C, \hat{P}^M) \quad (59)$$

under \mathbb{P}_2

Note that the evaluation of the actual revenues needs to be done using the true cost function J . This involves replacing the computed optimal prices $\hat{\pi}^{*C}$ and \hat{P}^M obtained from \mathbb{P}_3 in the ground truth equation (43), *i.e.*

$$\hat{x}^*(t) = f(x^*(t), \hat{\pi}^{*C}, \hat{P}^M, \Delta P_l, t) \quad (60)$$

Finally, we use this ground truth solution to evaluate the effective utility revenues $J(x^*, \hat{\pi}^{*C}, \hat{P}^M, \pi^M)$. Note that this value will depend on the particular sequence ΔP_l , resulting from the difference between power demand and power production variability in the daily profile.

VI. SIMULATION RESULTS

In this section, we showcase two simulation scenarios. The first is devoted to evaluating the distance to the optimal solution, while the second intends to evaluate the cost revenue for the EV users and the CSO resulting from participation in the FCR market.

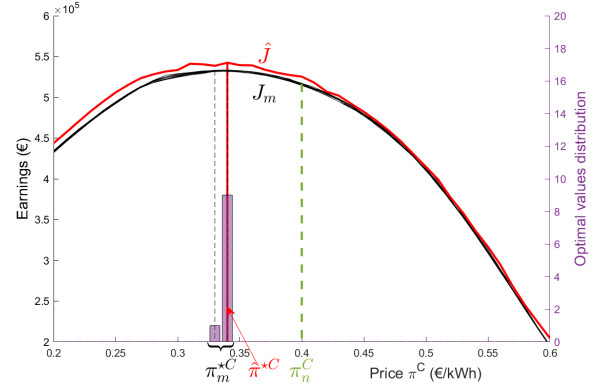


Fig. 6: Comparisons are made between \hat{J} (red curve) and J_k (black curve). The vertical red line represents $\hat{\pi}^{*C} = 0.34$, while the black dashed lines represent various $\pi_m^{*C} \in 0.33, 0.34$ obtained. The green dashed line represents the nominal price $\pi_n^C = 0.4$. The purple bar plot illustrates the distribution of π_m^{*C} .

A. Distance to optimal

Let $\pi^C \in \Pi^C \triangleq \{0.2, 0.21, 0.22, \dots, 0.6\}$, with Π^C being the admissible set for π^C . Let us also consider a set, $\Lambda_P \triangleq \{\Delta P_l^m, \forall m = 1, 2, \dots, 10\}$, of realizations for ΔP_l that will be used for this evaluation. Note that ΔP_l^m is stochastic in our simulations. We consider the following experiment.

- 1) For all $\pi^C \in \Pi^C$, and for each realization $\Delta P_l^m \in \Lambda_P$, solve \mathbb{P}_1 (*i.e.* compute $\pi_m^{*C}, \forall m$), and record the resulting ideal cost $J_m(x_m, \pi^C, P^M, \Delta P_l^m)$.
- 2) For all $\pi^C \in \Pi^C$ solve \mathbb{P}_3 (*i.e.* compute $\hat{\pi}^{*C}$), and record the resulting cost upperbound $\hat{J}(\hat{x}, \pi^C, \hat{P}^M)$.

Fig. 6 shows the results. From this figure we can first observe that the optimization problem is indeed convex. We can also see that the upper bound \hat{J} results in a tight bound for J , and allows us to obtain a value for $\hat{\pi}^{*C} = 0.34$ which is very close to those of π_m^{*C} obtained from solving the "ideal" optimal problem. Finally, note that all the resulting π_m^{*C} are concentrated in only two values, $\{0.33, 0.34\}$ for the 10 random realization of ΔP_l , and that the value $\pi_m^{*C} = 0.34$ repeats 9 times out of 10. Therefore, 90% of the time, $\pi_m^{*C} = \hat{\pi}^{*C}$, and 10% of the time, there is a 0.01€ difference.

Finally, note that the electricity price to be sold to the EV users with this optimisation strategy is substantially lower than the one of the "nominal" (without entering the FCR market) electricity price $\pi_n^C = 0.4$ €. Specifically, $\hat{\pi}^{*C}$ is 15% lower than π_n^C , resulting in:

$$0.34\text{€} = \hat{\pi}^{*C} < \pi_n^C = 0.4\text{€} \quad (61)$$

B. FCR market profit evaluation

Let us now evaluate the profits incurred by the CSO thanks to its participation to the FCR market. Consider the previous realization set Λ_P for ΔP_l . Assume that the CSO sells electricity at the nominal price $\pi_n^C = 0.4$ € without participating to the FCR market. The CSO revenues are:

$$J_n = \int_0^T \pi_n^C \tilde{P}_n dt \quad (62)$$

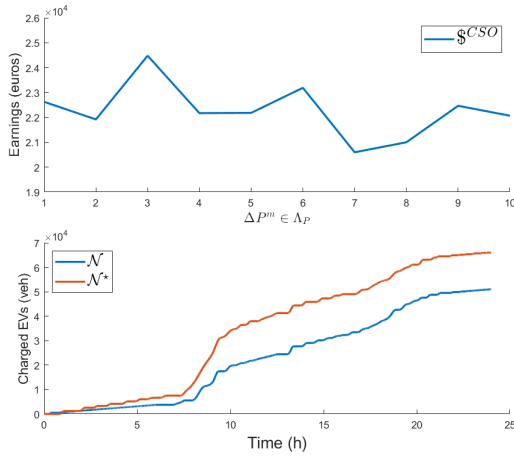


Fig. 7: Numerical results for CSO revenues from equation (64) and number of vehicles charged by the charging station.

where \tilde{P}_n results from solving problem \mathbb{P}_1 with $\pi^C = \pi_n^C$. However, when the CSO enters the market, the CSO optimal revenues are:

$$J^* = \int_0^T \hat{\pi}^{*C} \tilde{P}^* dt + \sum_{k=1}^6 \pi_k^M \hat{P}_k^M \quad (63)$$

where $\hat{\pi}^{*C}$ comes from solving problem \mathbb{P}_3 , and $\tilde{P}^*(x^*)$ from solving the ground true system (60), with the optimal value $\hat{\pi}^{*C}$. Revenues for the CSO are then computed:

$$\mathcal{S}^{CSO} = J^* - J_n \quad (64)$$

The total profit generated by the CSO \mathcal{S}^{profit} can be determined by deducting the electricity purchase cost from the revenue earned :

$$\mathcal{S}^{profit} = \int_0^T (\hat{\pi}^{*C} - \pi^{spot}) \tilde{P}^* dt + \sum_{k=1}^6 \pi_k^M \hat{P}_k^M$$

Where π^{spot} refers to the fluctuating electricity purchase price throughout the day.

An EV is considered charged when it leaves the charging station. We compute the number of EVs served (charged) at the CS during a 24hr day period, $\mathcal{N}, \mathcal{N}^*$ for nominal price π_n^C , and optimal price $\hat{\pi}^{*C}$, respectively.

$$\mathcal{N} = \int_0^T \varphi_{out,n} dt, \quad \mathcal{N}^* = \int_0^T \varphi_{out}^* dt \quad (65)$$

$\varphi_{out,n}$ and φ_{out}^* results from solving (60) for π_n^C and $\hat{\pi}^{*C}$.

Fig. 7 illustrates the respective revenues as a function of the different realizations. The average profit increase for the CSO, denoted as \mathcal{S}_k^{CSO} , is 22,700€, with 1,476.80€ coming from the sale of capacity on the FCR market. The remainder of the profit increase is attributed to a higher influx of EVs due to the more attractive pricing, as depicted by the comparison between \mathcal{N} and \mathcal{N}^* .

VII. CONCLUSIONS

In this study, we have presented an approach for integrating CSO into the FCR market using a mobility model, an aggregated charging station model, and an FCR market model. Despite the challenge of predicting the FCR market settlement price, we have proposed a bidding strategy for

CSO in the FCR market and an energy pricing strategy. Our findings suggest that CSO participation in the FCR market leads to increased revenue for CSO while simultaneously reducing charging costs for EV users. Future research could extend this work by considering competition among multiple charging stations and exploring the applicability of this strategy to larger-scale mobility models. Additionally, further investigation into the impact of CSO participation on grid stability and overall market dynamics would be valuable.

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