

# Comparison of optimized interferential stimulation using two pairs of electrodes and two arrays of electrodes\*

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**Abstract**—Interferential stimulation (IFS) or Temporal Interference (TI) has recently generated considerable interest as computational models show that it can focally stimulate deep brain regions with non-invasive transcranial electrical currents [1]. However, the proposed solution in [1] requires two arrays, involving dozens of electrodes in each, to achieve optimal focality in the deep brain regions. Implementation of this approach is usually not feasible in practice due to the limited number of channels and the associated accuracy and precision needed in current stimulation devices. Alternative method [2] focuses on using only two pairs of electrodes as proposed in the conventional IFS approach and searching exhaustively in the parameter space for the optimal montage that maximizes the focality of the modulation at the deep target. Here we compare these two methods in terms of the quality of the solutions (focality versus modulation depth) and the practicality (speed and number of electrodes needed). We then give general guidelines for optimal IFS in practice for future studies.

## I. INTRODUCTION

Interferential stimulation (IFS) or Temporal Interference (TI) applies sinusoidal waveforms of similar frequency through two pairs of electrodes [3]. However, un-optimized IFS does not show any significant advantage over conventional high-definition transcranial electrical stimulation [4]. There have been efforts to optimize the focality of IFS [5], [6], [2], but these are limited to two pairs of electrodes as originally proposed by [3]. We recently presented a rigorous framework for optimizing IFS using two arrays of electrodes [1], but results showed that dozens of electrodes are needed to achieve optimal focality, especially for targets in the deep brain regions. In practice, limited number of channels with the requisite accuracy and precision at the IFS frequencies are available in current stimulation hardware options. To make our solution feasible, here we limit the number of electrodes (i.e. channels) and compare that with the recently published method using exhaustive search on two pairs of electrodes [2]. We discuss the pros and cons of each method and provide general guidelines for future practice involving optimized IFS.

## II. METHODS

Data from three adult male neurologically normal subjects (30, 36 and 46 years old) previously considered [7] were used in this computational study. We named their head models

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as H1, H2, and H3, respectively. T1-weighted magnetic resonance images (MRI) were acquired from a 3-T MRI scanner with a resolution of 1 mm<sup>3</sup>, see [7] for detailed acquisition parameters. To generate the lead field [8], [9] that is needed for targeted IFS, a fully-automated toolbox ROAST was used [10]. With a simple one-line command [11], ROAST generates the lead field for each of these subjects from their T1 MRIs. 72 electrodes following the international 10/10 system [12] were placed on the scalp surface by ROAST in this process.

We first replicated the exhaustive search process for an optimal montage using two pairs of electrodes, as implemented in [2]. The same target location in the deep brain region was selected as in [2], i.e., the head of the right hippocampus. Exhaustive search was performed across: (1) four possible electrodes selected from the 72 placed electrodes on the scalp; (2) three possible ways of pairing in these four electrodes for the two frequencies used in IFS; (3) amplitudes of injected current at one pair of electrodes, in the range of 0.5 mA to 1.5 mA, with a step size of 0.05 mA and the sum across the two pairs of electrodes being 2 mA. See [2] for more details. In total 64,813,770 montages were considered for each target in each head model (1,028,790 possible combinations of 4 electrodes  $\times$  3 possible ways of pairing  $\times$  21 amplitudes of injected current). The optimal montage is the one that achieves maximal ratio of peak modulation depth at the target to that at the non-target region (Eq. 3 in [2]). See [4] for the definition of modulation depth. Note that in our implementation, we computed the modulation depth along the radial direction, i.e., the direction pointing from the target location to the center of the brain (defined as MNI coordinates of [0,0,0]), instead of the modulation depth along the direction of maximal modulation as in [2]. We preferred radial direction as performing another internal search for maximal modulation direction would increase the computational load of the exhaustive search process that is already computationally intensive (takes about 2 days to find one solution).

We then replicated the more rigorous formulation in optimizing the focality of IFS using two arrays of electrodes. We implemented Eq. 18 in [1], with the power constraint on non-target region starting from  $P_{max} \times 10^8$  and reducing to  $P_{max} \times 10^{-3}$ , where  $P_{max}$  was obtained from the lead field and specified target location (see [1], [13] for details). This uses most of the electrodes in the full array of 72 electrodes, which is usually not practical as most stimulation devices do not have more than 32 channels. To reduce the electrodes needed in the solution, we only used the top  $K$  electrodes

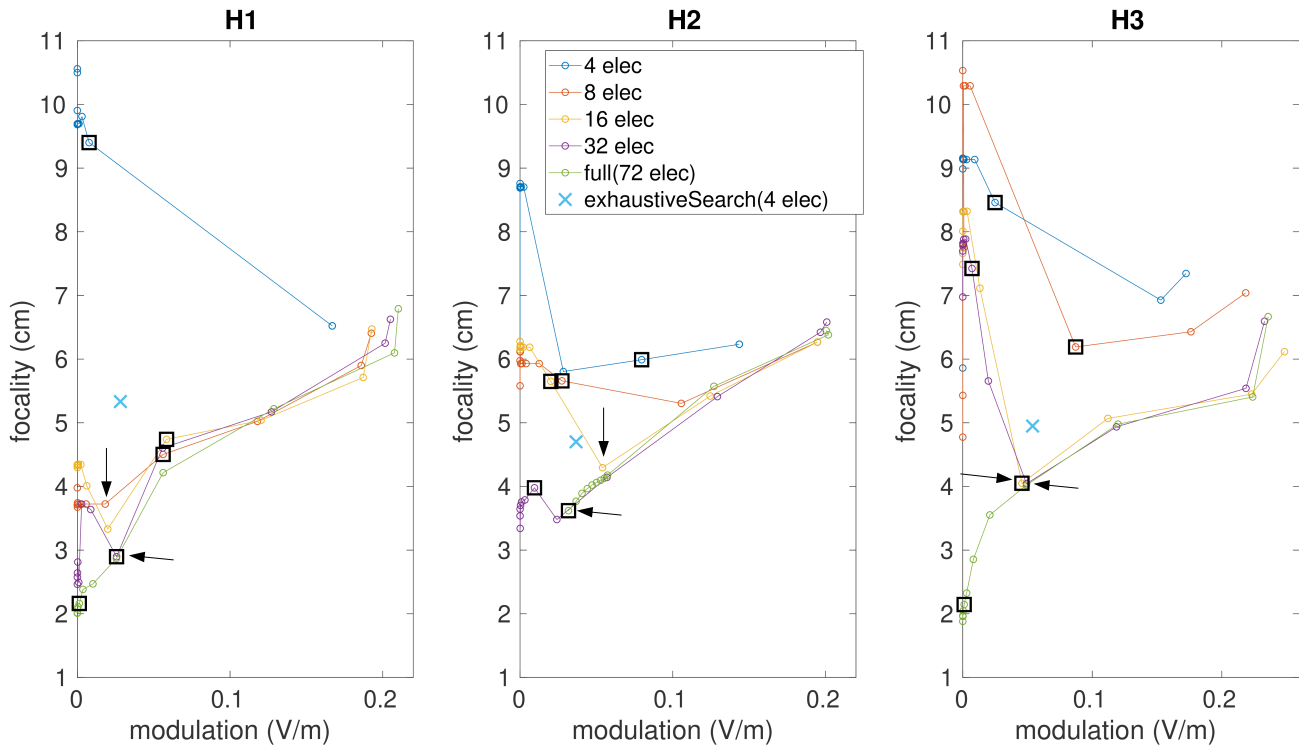


Fig. 1. Relationship between focalcity (cm) and modulation depth (V/m) across the three subjects considered (H1–H3). Circles on the curves are solutions from rigorous optimization across two arrays of electrodes [1], with different curves representing different numbers of total electrodes used for stimulation under different power constraints. The full array contains 72 electrodes. Blue crosses indicate solutions from exhaustive search using two pairs of electrodes [2]. Black squares on the curves indicate injected current reaches the safety limit of 2 mA. Circles indicated by arrows are visualized in Figure 2.

( $K \leq 32$ ) that receive the most currents. As the solutions can be different corresponding to different levels of the power constraint  $P_{max}$  (green curves in Figure 1), we first identified the solution  $s$  that gives the closest modulation depth to the one achieved by the solution from exhaustive search, and then we sorted the absolute values of the injected current in  $s$  for each of the two frequencies and took out the top  $K/2$  electrodes for each frequency. Lead field corresponding to these  $K$  electrodes ( $K/2$  for each frequency) was taken out and re-referenced to the electrode with the smallest absolute value of injected current in these  $K$  electrodes. This subset of lead field was used to re-run the same optimization as in Eq. 18 in [1], with the same 12 levels of power constraints mentioned above. The final solution only has up to  $K$  electrodes (see Figure 2C).

For each solution, the modulation depth and its focalcity at the target location were computed. The focalcity is defined as the cubic-root of the brain volume with modulation depth of at least 50% of the modulation at the target [4]. All computation times (CPU time in Figure 2) reported were measured on a workstation with Intel® Xeon® Silver 4114 CPU at 2.20 GHz.

### III. RESULTS

Figure 1 shows the focalcity–modulation curves for all the solutions for targeting the right hippocampus in the

three head models using different methods. Results from the exhaustive search on two pairs of electrodes [2] are shown as blue crosses, and those from the rigorous optimization using two arrays of electrodes [1] are plotted as circles, with different colors representing different numbers of total electrodes used in the montages. Circles are connected assuming linear interpolation. It is clear that the rigorous optimization using full array of 72 electrodes can give solutions that have better focalcity than the exhaustive search using only two pairs of electrodes under the same level of modulation depth (comparing blue crosses with green curves). The focalcity decreases as the intensity of modulation increases (green curves), as dictated by the theoretical research [14]. However, as we reduce the electrode numbers in the solutions, the focalcity–modulation curves are not strictly monotonic, especially if the total injected current is smaller than the safety limit in transcranial stimulation of 2 mA (left of black squares on the purple, orange, red and blue curves). For the three head models, rigorous optimization with  $K = 4$  electrodes gives solutions with worse focalcity compared to that from the exhaustive search (blue curves vs. blue crosses). For H2 and H3, even using  $K = 8$  electrodes in the rigorous optimization cannot achieve the same performance in focalcity as the exhaustive search (red curves vs. blue crosses). This is because with 8 or fewer electrodes, the optimization has difficulty finding the solution that satisfies the objective

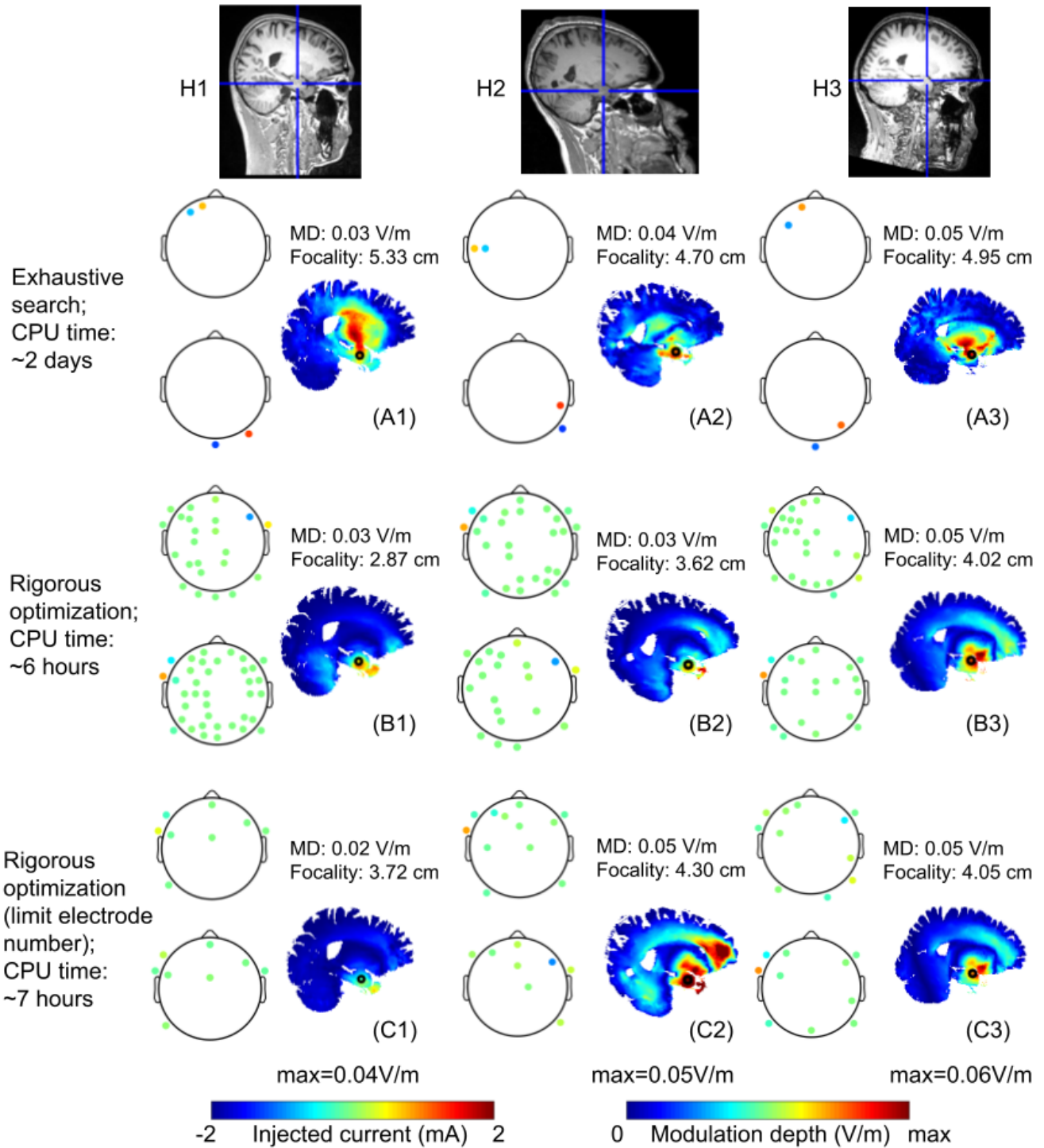


Fig. 2. Exemplary cases of electrode montages and distributions of the modulation depth for the exhaustive search using two pairs of electrodes [2] and the rigorous optimization across two arrays of electrodes [1]. These examples are taken from those data points indicated by arrows and the blue crosses in Figure 1. (A) Exhaustive search; (B) rigorous optimization; (C) rigorous optimization with  $K = 8$  electrodes for H1, and  $K = 16$  electrodes for H2 and H3. The two topoplots in each panel show the montage for each frequency in the interferential stimulation. CPU time for each method is noted. Focality and modulation depth (MD) for each solution is also indicated in each panel.

